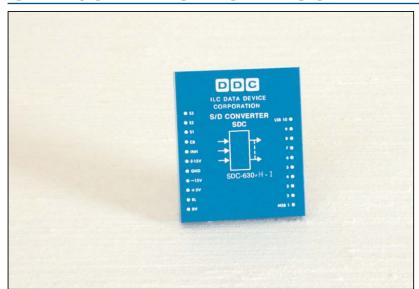
SDC-630/632/634*

10-, 12-, 14-BIT SYNCHRO-TO-DIGITAL OR RESOLVER-TO-DIGITAL CONVERTER





The SDC-630/632/634 series are low cost, low profile Synchro-to-Digital (S/D) and Resolver-to-Digital (R/D) tracking converters with standard pin configurations. They use a unique control transformer algorithm that provides inherently higher accuracy and jitter-free output. Utilizing a type II servo loop, these converters have no velocity lag up to the specified tracking rate, and output data is always fresh and continuously available. Each unit is fully trimmed and requires no adjustment or field calibration.

APPLICATIONS

These converters may be used wherever analog angle data from a synchro or resolver must be rapidly and accurately converted to digital form for transmission, storage or analysis. Because these units are extremely rugged and stable, and meet the requirements on MIL-STD-202E, they are suitable for the most severe industrial, commercial and military applications. Military ground support and avionics uses include ordnance control, radar tracking systems, navigation and collision avoidance systems.

- **FEATURES**
 - Standard Low Profile Converters with Optional Velocity Output
 - Signal and Reference Input:
 - Internal Transformer Isolation
 - All Common L-L Levels and Frequencies
 - · Accuracy:

10 Bit: 21 Minutes 12 Bit: 8.5 Minutes

14 Bit: 4 Minutes, 0.9 LSB or

2.6 Minutes (High Accuracy)

Make sure the next Card you purchase

- Logic:
 - TL Compatible
 - Parallel Binary Angle Output
- Power Required:
 ±15 VDC and +5 VDC
- For new designs see DDC SDC-630/632/634*A/ST Series Data Sheet

* Patented



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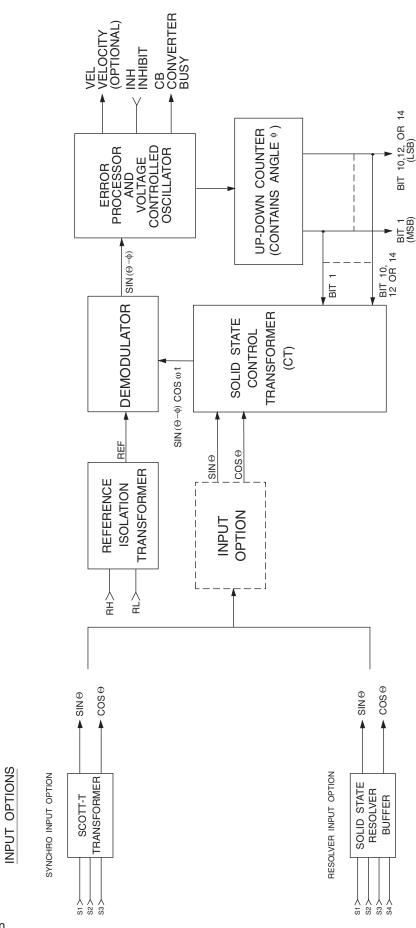


TABLE 1. SDC-630/632/634 SPECIFICATIONS

(Apply over temperature range, power supply range, reference frequency and amplitude range, ±10% signal amplitude variation, and up to 10% harmonic distortion in the reference.)

| PARAMETER | VALUE | | | | |
|--|---|---------|---|-----------------------------|--|
| PANAMETER | SDC-630 | SDC-632 | | SDC-634 | |
| RESOLUTION | 10 bits | 1: | 2 bits | 14 bits | |
| ACCURACY Standard Units High Accuracy Option | ±21 min | ±8 | .5 min | ±4 min ±0.9 LSB ±2.6 min | |
| SIGNAL AND REFERENCE INPUT | Signal Frequend Range | су | Signal Input y Impedance (L-L Balanced, Resis | | |
| Synchro Input* 90V L-L, 400 Hz (Option H) 90V L-L, 60 Hz (Option I) 11.8V L-L, 400 Hz (Option L) Resolver Input* | 350-1000 47-1000 350-1000 | Hz | 148 kΩ min 19 kΩ min 198 kΩ min 57 kΩ min | | |
| 90V L-L, 400 Hz (Option H) 26V L-L, 400 Hz (Option M) 11.8V L-L, 400 Hz (Option L) | 350-1000 350-1000 350-1000 | Hz | | | |
| REFERENCE INPUT* | Reference Voltage Range | | Reference Input Impedance (Resistive | | |
| Options H, I Options M, L | 40-150 Vrms 300 kΩ min 10-50 Vrms 80 kΩ min | | | | |

^{*}Transformer Isolated. Other voltages and frequencies available on special order.

| DIGITAL INPUT/OUTPUTS | |
|--|---|
| Logic Type Inhibit Input (INH) Loading | TTL Logic "0" inhibits 0.2 Std. TTL loads plus 18 KΩ min pull-up resistor to +5V supply |
| Outputs Type | Low power Schottky (can drive remote loads) |
| 10, 12, or 14 Parallel Data Bits | Natural Binary Angle; Positive logic |
| Converter Busy (CB) | 0.5 to 1.5 µsec positive pulse. Data changes on leading edge. |
| Drive Capability | 2 Std. TTL loads |
| VELOCITY OUTPUT (ON SPECIAL ORDER ONLY) | |
| Туре | Derived from an op-amp with low impedance output. Positive Output for increasing angle |
| Voltage Range | 10V Min |
| Scale Factor (for SDC-634 - Others on Request) Options H, M, and L Option I | 6V per rps nominal (10V = 15 rps) 3.3V per rps nominal (10V = 2.7 rps) |

TABLE 1. SDC-630/632/634 SPECIFICATIONS (CONT.)

(Apply over temperature range, power supply range, reference frequency and amplitude range, ±10% signal amplitude variation, and up to 10% harmonic distortion in the reference.)

| to 10% Harmonic distortion in the reference.) | | | | | | | | |
|--|--------------------------------|---|--------------|---|--------------|---|-------------|--|
| PARAMETER | | | VALUE | | | | | |
| | | SDC-630 | | SDC-632 | | SDC-634 | | |
| RESOLUTION | | 10 bits | | 12 bits | | 14 bits | | |
| DYNAMIC CHARACTERISTIC | S | Min | Тур | Min | Тур | Min | Тур | |
| Input Rate for Full Accuracy (Min Rang Options H, M, L (40 Option I (60 Hz) | | 0-22 rps 0-8 rps | | 0-40 rps 0-10 rps | | 0-10 rps 0-1.25 rp | | |
| Acceleration for 1 LSB Lag Options H, M, L (400 Hz) Option I (60 Hz) | | | | 4500°/sec ² typ 295°/sec ² typ | | | | |
| Settling Time For Normal Tracking (Up to Specified Input Rate) For 179° Step Change (Typical Values) Options H, M, L (400 Hz) Settling to 1 LSB Settling to Final Value Option I (60 Hz) | | No lag error | | No lag error | | No lag error | | |
| | | 80 msec 100 msec | | 90 msec 110 msec | | 150 msec 200 msec | | |
| Settling to 1 LS Settling to Final | | 300 ms 500 ms | | 300 m 360 m | | 800 msec 1000 msec | | |
| Velocity Constant (Transcription Servo loop) | ype II | Κγ= ∞ | | K y= ∞ | | K y= ∞ | | |
| Acceleration Constant (Nominal Values) Options H, M, L (400 Hz) Option I (60 Hz) | | K _a =36,000sec ² K _a =2,200sec ² | | | | K _a =27,800sec ² K _a =900sec ² | | |
| POWER SUPPLIES Nominal Voltage | POWER SUPPLIES Nominal Voltage | | +15 V Supply | | -15 V Supply | | +5 V Supply | |
| Voltage Range Maximum Voltage Without Damage | | +11 to +16.5 V +18 V | | -11 to -16.5 V -18 V | | +4.5 to - | | |
| SDC-634 Typic | imum | 8 mA 13 mA 10 mA 15 mA | | 18 mA 30 mA 20 mA 30 mA | | 80 mA 120 mA 100 mA 150 mA | | |
| TEMPERATURE RANGES | | | | I | | I | | |
| Operating -1 Option -3 Option Storage | | -55°C to +105°C 0°C to +70°C -55°C to +125°C | | | | | | |
| PHYSICAL CHARACTERISTIC Size (Encapsulated Module) | s | 3.125 x 2.625 x 0.435 inches (7.94 x 6.67 x 1.10 cm) | | | | | | |
| Weight | | 4 oz (113 gm.) | | | | | | |

TECHNICAL INFORMATION

TIMING

FIGURE 2 shows the timing waveforms of the converter. Whenever an input angle change occurs, the converter changes the digital angle in steps of 1 LSB, and generates a converter busy impulse (CB). The CB is a positive pulse 0.5 to 1.5µsec long. Data changes on the leading edge of the CB pulse, and data can be transferred 0.5µsec after the leading edge.

The simplest method of interfacing with a computer is to transfer data at a fixed time interval after the inhibit is applied. The converter will ignore an inhibit applied during the "busy" interval until that interval is over. Timing is as follows: (a) apply the inhibit, (b) wait 0.5µsec, (c) transfer the data, and (d) release the inhibit. Extra CB pulses will not occur if the input angle changes while the counter is locked by the INH.

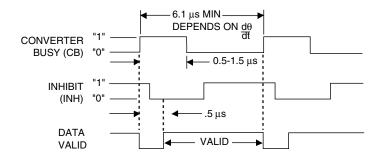


FIGURE 2. SDC-630/632/634 TIMING DIAGRAM

DYNAMIC PERFORMANCE

A type II servo loop (KV = ∞) and very high acceleration constants give these converters superior dynamic performance, as listed in the specifications. If the power supply voltages are not the +15 VDC nominal values, the specified input rates for full accuracy will increase or decrease in proportion to the fractional change in voltage. The +15 V supply voltage will determine the positive maximum velocity, and the -15 V supply voltage will determine the negative maximum velocity.

So long as the maximum tracking rate is not exceeded, there will be no lag in the converter output. If a step input occurs, as is likely when the power is initially turned on, the response will be critically damped. FIGURE 3 shows the response to a step input. After initial slewing at the maximum tracking rate of the converter, there is one overshoot which is inherent to a Type II servo. The overshoot settling to a final value is a function of the small signal settling time.

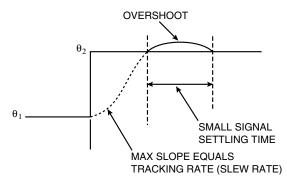


FIGURE 3. RESPONSE TO A STEP INPUT

The nominal open loop transfer function is given by

$$A^{2} \left(\frac{S}{B} + 1 \right)$$

$$G = \frac{S^{2} \left(\frac{S}{10B} + 1 \right)}{S^{2} \left(\frac{S}{10B} + 1 \right)}$$

where the parameters A and B are:

| TABLE 2. TRANSFER FUNCTION PARAMETERS | | | | | | |
|---------------------------------------|---|-----------------------|-----------------------|-----------------------|--|--|
| | | SDC-630 | SDC-632 | SDC-634 | | |
| 400 Hz | А | 190 sec ⁻¹ | 226 sec ⁻¹ | 167 sec ⁻¹ | | |
| 400 HZ | В | 91 sec ⁻¹ | 100 sec ⁻¹ | 56 sec ⁻¹ | | |
| 60 Hz | Α | 46 sec ⁻¹ | 58 sec ⁻¹ | 30 sec ⁻¹ | | |
| 60 HZ | В | 23 sec ⁻¹ | 26 sec ⁻¹ | 10 sec ⁻¹ | | |

POWER SUPPLIES

The main power supplies can vary over their specified ranges with no change in the converter specifications except for a proportional change in the maximum tracking rates.

When testing or evaluating the converters, it is advisable to limit the current to each of the three power supplies. Set each limit to 50% greater than the maximum current listed for that supply in the specifications table.

TRANSFORMER INPUT

To prevent damage to the input transformers, the maximum steady state voltage should not exceed the specified input voltage by more than 30%. The maximum common mode voltage (DC plus recurrent AC peak) should not exceed 500 V.

ACCOMMODATING NON-STANDARD INPUT VOLTAGES

The signal and reference input levels of the SDC-630 series can be resistively scaled to accommodate non-standard voltages. A converter should be selected that is the next lower standard voltage and the voltage is then scaled up with resistors in series with the synchro and/or reference inputs.

For a synchro input (SDC), a resistor R_{SIG} is added in series with S1, S2 and S3, which is determined as follows:

R_{SIG} = 1.11K (New L-L Voltage - Standard Unit Voltage)

That is, 1.11K for each volt above that for which the standard unit is designed.

Example: An SDC-634-L (11.8V) is to be used at 50V L-L.

 $R_{SIG} = 1.11K (50-11.8) = 42.4K$

The closest available high grade resistor with a low temperature coefficient of resistance should be used, and the three resistors should be matched to each other as closely as possible. In general, a 0.1% difference will introduce 1.7 arc minutes of additional error due to the effect on SIN ratio relationship.

The ABSOLUTE value of the resistor is not critical.

In the case of the RESOLVER version (RDC), the equation is:

R_{SIG} = 2.2K (New L-L level - Standard Unit L-L level)

The calculated resistors are connected in series with S1 and S2 respectively. Note only two resistors are required. The required resistor matching and its effect on accuracy, is the same as for a synchro input (See FIGURE 4).

The Reference Voltage treatment is similar, but the value selected is not critical.

R_{Ref} = 2.8K (New Ref - Standard Ref)

Here, even a 10% tolerance is adequate.

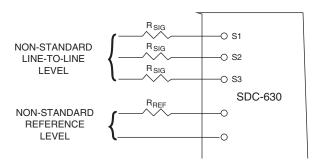
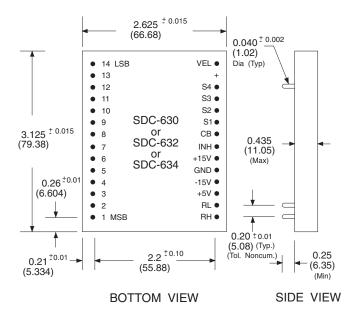


FIGURE 4. SIGNAL AND REFERENCE SCALING

Dimensions in inches (mm).

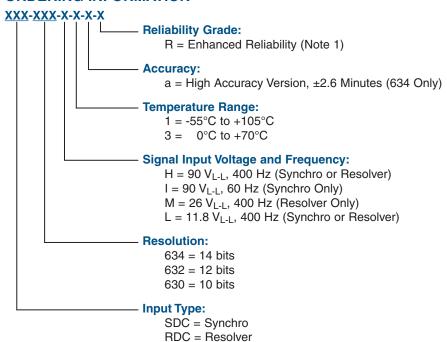


Notes:

- 1. Case material is glass filled Diallyl Phthalate per MIL-M-14, Type SDG-F.
- 2. Pins 13 and 14 are omitted for SDC-632, and pins 11, 12, 13, and 14 are omitted for SDC-630.
- 3. Pin VEL is present only if requested on special order.
- 4. Pin S4 is present on Resolver units, and omitted on Synchro units.
- 5. + = No PIN
- 6. Serial Number engraved on side of case.

FIGURE 5. SDC-630/632/634 MECHANICAL OUTLINE

ORDERING INFORMATION



Notes:

- 1. R version only available in -55°C to 105°C temperature range (Option 1). "R" Enhanced reliability processing provides an 105°C burn-in.
- 2. Available Sockets

P/N 9010 = socket to barrel ends for soldering direct to socket pins

P/N 9046 = socket to pin ends to solder socket to PCB

P/N 9050 = socket to wire wrap pins

The lead finish for the machined pins is SN60/PB40.The internal circuits of this completed module contain lead.

| STANDARD DDC PROCESSING FOR DISCRETE MODULES/PC BOARD ASSEMBLIES | | | | | | |
|--|-----------|--------------|--|--|--|--|
| TEST | METHOD(S) | CONDITION(S) | | | | |
| INSPECTION / WORKMANSHIP | IPC-A-610 | Class 3 | | | | |
| ELECTRICAL TEST | DDC ATP | _ | | | | |

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Specifications are subject to change without notice.

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